

LIST OF CURRENT CLAIMS

1. (Currently Amended) A walk simulating machine comprising:

~~A base;~~ a base;

~~[[A]]~~ a crank unit fixed on an upper rear portion of said base and having two cranks respectively pivotally connected ~~pivotaly~~ with ~~two~~ opposite sides of the crank unit, said two cranks located with an angular difference of 180 degree-difference degrees therebetween;

~~[[A]]~~ a front post fixed on and extending upward on ~~on~~ from a front end of said base, the front post having a horizontal rod extending to the right side and the left side of the front post, ~~a hand-slide base~~ two roller supporting members respectively connected pivotaly at two outer sides ends of said horizontal rod;

~~Two~~ two pedal connect rods located respectively at two sides of said base, respectively having their rear ends pivotally connected with said cranks of said crank unit ~~[[and]]~~ each pedal connect rod having a pedal fixed thereon;

~~Two~~ two side connect rods respectively located at two sides of said front post and respectively consisting of an upper connect rod and a lower connect rod ~~pivotaly~~, said upper connect rod having its lower end pivotally connected with an upper end of said lower connect rod, said upper connect rod having its upper end pivotally connected with said horizontal rod, a stop member located at the front of said upper connect rod, said upper connect rod having a swaying stage and a not-swayable stage set by said stop member in case said upper connect rod is stopped by said stop member, said lower connect rods having its lower ends pivotally connected with front ends of said pedal connect rod; and~~[[,]]~~

~~Two~~ two hand gripping rods respectively located at two sides of said base, respectively having ~~it's~~ a lower end pivotally connected with a front end of each said pedal connect rod and ~~its~~ an upper end extending through an aperture between two slide rollers of said ~~hand-slide base for two hands of a user to grip with~~ roller supporting member.

2. (Currently Amended) The walk simulating machine as claimed in ~~Claim~~ claim 1, wherein said stop members are controlled by a slope adjuster, which moves and adjusts said stop members ~~in their gaps~~ relative to said upper connect rods so that the swaying stage and the not-swaying stage of said upper connect rod can be adjusted, and therefore such that a walking orbit of said pedals can be adjusted into three modes for making a horizontal, a sloping-up or a sloping-down pedaling exercise.

3. (Currently Amended) The walk simulating machine as claimed in ~~Claim~~ claim ~~[[1]]~~ 2, wherein said slope adjuster includes a slope rod passing horizontally through said front post below said horizontal rod ~~to two sides, a crank~~ two slope adjuster cranks respectively fixed at two ~~sides~~ ends of said slope rod ~~and~~ , each said slope adjuster crank being pivotally connected with one of said stop ~~member~~ members to locate said stop members in front of each said upper connect rod respectively, a position disk having one surface fixed with said front post and the other surface provided with a plurality of angle recesses spaced apart to have angle differences, an L-shaped adjust rod having its upper end fixed with said position disk, a ~~tenon~~ locking pin having one end laterally passing through said adjust rod and fitting in one of said angle recesses of said position disk and having a spring to elastically push the end to securely fit in one of said angle recesses, and a push rod having its intermediate portion pivotally connected with said adjust rod and its one end extending in the connect point of said ~~tenon~~ locking pin and said adjust rod, said push rod pushed to control the end of said ~~tenon~~ locking pin to retreat from one of said angle recesses for changing the position of said stop rod.

4. (Currently Amended) The walking simulating machine as claimed in ~~Claim~~ claim ~~[[1]]~~ 3, wherein said slope adjuster has the slope rod laterally passing horizontally through said front post below said horizontal rod ~~to two sides, said stop member pivotally connected with each said crank; and~~ an electric control device is provided to drive said slope rod to shift to set a biasing angle of said slope rod so as to control a position angle of said stop member relative to said upper connect rods.